

EAV94279

V1.2

ATV6xx - Communication Parameters

DANGER

UNINTENDED EQUIPMENT OPERATION

- Read and understand the programming manual before operating the drive.
- Any changes made to the parameter settings must be performed by qualified personnel.

Failure to follow these instructions will result in death or serious injury.

WARNING

LOSS OF CONTROL

- The designer of any control scheme must
 - consider the potential failure modes of control paths and, for certain critical control functions,
 - provide a means to achieve a safe state during and after a path failure.
 Examples of critical control functions are emergency stop and overtravel stop.
 - Separate or redundant control paths must be provided for critical control functions.
 - System control paths may include communication links. Consideration must be given to the implications of unanticipated transmission delays or failures of the link. (see note a.)
- Failure to follow these instructions can result in death, serious injury, or equipment damage.

Note a.: For additional information, refer to NEMA ICS 1.1 (latest edition), "Safety Guidelines for the Application, Installation, and Maintenance of Solid State Control" and to NEMA ICS 7.1 (latest edition), "Safety Standards for Construction and Guide for Selection, Installation and Operation of Adjustable-Speed Drive Systems."

Electrical equipment should be installed, operated, serviced, and maintained only by qualified personnel. No responsibility is assumed by Schneider Electric for any consequences arising out of the use of this material.

EXPLANATORY NOTE

This Excel file is for reference only. Refer to programming manual and communication protocols manuals for full information.

This Excel file can be used to carry out searches (example: parameter address and format) and sort operations.

The columns include the following criteria:

Code: Language-independent, this allows a rapid search in the programming manual, which includes an index of parameter codes. Additional information can be found in the Communication Manuals (Modbus, CANopen....etc.....)

Name: Parameter designation

Logic address: Address for the Modbus messaging are in decimal and hexadecimal (preceded by 16#) format. To optimize Modbus messaging performance, two addresses are given for the control word (CMD) and the status word (ETA). The addresses annotated "speed" are for use in rpm; the addresses annotated "frequency" are for use in Hz.

CANopen index: CANopen index/subindex in hexadecimal format, to be used for variable assignment of PDOs and SDO messaging.

PROFIBUS index: Address for PROFIBUS

CIP : Address for DeviceNet

Class/instance/attribute in decimal and hexadecimal (preceded by 16#) format.

When two paths are given, for example:

- 16#29/01/0D = 41/1/13 (messaging): ODVA standard path. It can be used for explicit messaging. Do not use it for configuring an assembly.
- 16#8C/01/07 = 140/1/7 (assembly): Altivar-specific path. This is the path that must be used for configuring an assembly. Avoid using it for explicit messaging, to ensure better interchangeability.

Link: For WORD type parameters, a dynamic link opens the description of a bit register or a listing. Listings are common to several parameters; only one part is valid for a given parameter. Refer to programming manual to determine the valid values. If an invalid value is written to a configuration parameter, the drive will indicate a fault [Invalid config.] (CFI).

Category: Defines the role of the parameter, for example: Command parameter, Status parameter, etc.

Access: Read and write options:

R: Read only

R/W: Read and write

R/WS: Read and write (write only possible when the drive is not in RUN mode).

It is not possible to write these parameters in "5-Operation enabled" or "6-Quick stop active" states.

If the parameter is written in the "4-Switched on" state, transition 10 to "2-Switch on disabled" is activated.

Type:

WORD (bit register): Word where each bit represents a command or a state

WORD (listing): Word where each value represents a possible choice for a configuration or state

INT: Signed integer

UINT: Unsigned integer

DINT: Signed double integer

UDINT: Unsigned double integer

Units: Physical unit and multiplier

Factory setting: Value of the parameter set at the factory.

Menu: Indicates the menus or menus where the parameter is located. Menu name displayed on the graphic display terminal, in square brackets [---], and menu code displayed by the 7-segment digits on the integrated display terminal, in round brackets (---).

Range: Possible values

Display: Parameter name displayed on the graphic display terminal, in square brackets [---], and parameter code displayed by the 7-segment digits on the integrated display terminal, in round brackets (---).

Menu: Indicates the menus or menus where the parameter is located. Menu name displayed on the graphic display terminal, in square brackets [---], and menu code displayed by the 7-segment digits on the integrated display terminal, in round brackets (---).

Order: Gives the initial storage order of the parameter in the file, from 1 to n. This makes it possible, after sorting operations, to put this file back in its initial

Table with columns: Code, Name, Logic address, CANopen index, DeviceNet path, Link, Category, Access, Type, Units, Factory setting, Range, Display, Menu, Order. Rows include parameters like NPLS (Low Speed), NSM (Nb Of Starts), OC0 (Eic Energy Cons), and many others up to PFHP (Pipe Fill Pressure).

Code	Name	Logic address	CANopen index	DeviceNet path	Link	Category	Access	Type	Units	Factory setting	Range	Display	Menu	Order
AV1J	AIV1 Lowest Process	16#11AA = 4522	16#200F/17	16#77/017B = 119/01/123	-	Configuration and settings	R/WS	INT (Signed16)	1	0	-32767 ... 32767	[AIV1 Lowest Process] (AU1J)	[LFU1-][AIV1 Sensor config.] (nPU1-)	1210
AV1K	AIV1 Highest Process	16#11B4 = 4532	16#200F/21	16#77/0185 = 119/01/133	-	Configuration and settings	R/WS	INT (Signed16)	1	0	-32767 ... 32767	[AIV1 Highest Process] (AU1J)	[LFU1-][AIV1 Sensor config.] (nPU1-)	1211
SPDM	Motor Mechanical speed	16#2EEB = 12011	16#205A/C	16#9D/010C = 157/01/12	-	Actual values parameters	R	UINT (Unsigned16)	Refer to programming manual		Refer to programming manual	Motor Mechanical speed] (SPdM)	[Pump parameters] (PPr-)	1212
DRC9	Ref Freq Channel	16#FB3F = 64319	=	=	=	CNL	R	WORD (Enumeration)	-		-			1213
DRCB	Ref Freq Channel	16#FB40 = 64320	=	=	=	CNL	R	WORD (Enumeration)	-		-			1214
DRCB	Ref Freq Channel	16#FB41 = 64321	=	=	=	CNL	R	WORD (Enumeration)	-		-			1215
DRCB	Ref Freq Channel	16#FB42 = 64322	=	=	=	CNL	R	WORD (Enumeration)	-		-			1216
DRCB	Ref Freq Channel	16#FB43 = 64323	=	=	=	CNL	R	WORD (Enumeration)	-		-			1217
DRCB	Ref Freq Channel	16#FB44 = 64324	=	=	=	CNL	R	WORD (Enumeration)	-		-			1218
DRCF	Ref Freq Channel	16#FB45 = 64325	=	=	=	CNL	R	WORD (Enumeration)	-		-			1219
DCC9	Command Channel	16#FB4A = 64330	=	=	=	CNL	R	WORD (Enumeration)	-		-			1220
DCCB	Command Channel	16#FB4B = 64331	=	=	=	CNL	R	WORD (Enumeration)	-		-			1221
DCCB	Command Channel	16#FB4C = 64332	=	=	=	CNL	R	WORD (Enumeration)	-		-			1222
DCCZ	Command Channel	16#FB4D = 64333	=	=	=	CNL	R	WORD (Enumeration)	-		-			1223
DCCD	Command Channel	16#FB4E = 64334	=	=	=	CNL	R	WORD (Enumeration)	-		-			1224
DCCE	Command Channel	16#FB4F = 64335	=	=	=	CNL	R	WORD (Enumeration)	-		-			1225
DCCF	Command Channel	16#FB50 = 64336	=	=	=	CNL	R	WORD (Enumeration)	-		-			1226
PFWU	Pipe Fill on Wake Up	16#3DBE = 15806	16#2080/7	16#B0/01/07 = 176/01/07	N Y	Configuration and settings	R/WS	WORD (Enumeration)	-	[Yes] (YES)	-	[Pipe Fill on Wake Up] (PFWU)	[Pipe fill] (PFI-)	1227
SLPL	Sleep Pressure Level	16#2DF2 = 11762	16#2057/3F	16#9B/01/A3 = 155/01/163	-	Configuration and settings	R/W	INT (Signed16)	call PressureUnitSelected [SUPR]	[No] (nO)	0 ... (call PressureUnitSelected [SUPR])	[Sleep Pressure Level] (SLPL)	[Sleep menu] (SLP-)	1228
WUPL	Wake Up Press level	16#2DF3 = 11763	16#2057/40	16#9B/01/A4 = 155/01/164	-	Configuration and settings	R/W	INT (Signed16)	call PressureUnitSelected [SUPR]	call PressureUnitSelected [SUPR]	Selected [SUPR]) ... (call PressureU	[Wake Up Press level] (WUPL)	[Wake up menu] (W P-)	1229

Code	Values	Display	Description	
ACT	0	[Not Done] (tAb)		
	1	[Pending] (PEnd)		
	2	[In Progress] (PrOG)		
	3	[Error] (FAIL)		
	4	[Autotuning Done] (dOnE)		
ACTION	0	[No action] (nO)		
	1	[Apply Autotuning] (YES)		
	2	[Erase Autotuning] (CLr)		
ADC	0	[No] (nO)		
	1	[Yes] (YES)		
	2	[Continuous] (Ct)		
AIOT	1	[Voltage] (10U)		
	2	[Current] (0A)		
	5	[Voltage +/-] (n10U)		
	7	[PTC MANAGEMENT] (PtC)		
	8	[KTY] (tY)		
	9	[PT1000] (1Pt3)		
	10	[PT100] (1Pt2)		
	11	[Water Prob] (LEUEL)		
	12	[3 PT1000] (3Pt3)		
	13	[3 PT100] (3Pt2)		
	14	[PT1000 in 3 wires] (1Pt33)		
	15	[PT100 in 3 wires] (1Pt23)		
	16	[3 PT1000 in 3 wires] (3Pt33)		
	17	[3 PT100 in 3 wires] (3Pt23)		
	ALR	0	[No Warning stored] (nOA)	
		1	[Fallback Frequency] (FrF)	
		2	[Speed Maintained] (rLS)	
3		[Type of stop] (Stt)		
4		[Ref Frequency Warning] (SrA)		
5		[Life Cycle Warn 1] (LCA1)		
6		[Life Cycle Warn 2] (LCA2)		
7		[Drive Running Warning] (drYA)		
8		[Low Flow Warning] (LFA)		
9		[High Flow Warning] (HFPA)		
10		[InPress Warning] (IPPA)		
11		[Low OutPres Warning] (OPLA)		
12		[High OutPres Warning] (OPHA)		
13		[PumpCycle warning] (PCPA)		
14		[Anti-Jam Warning] (JAMA)		
15		[Pump Low Flow] (PLFA)		
16		[LowPres Warning] (LPA)		
17		[Flow Limit activated] (FSA)		
18		[PID error Warning] (PEE)		
19		[PID feedback Warning] (PFA)		
20		[PID High Fdbck Warning] (PFAH)		
21		[PID Low Fdbck Warning] (PFAL)		
22		[Regulation Warning] (PISH)		
26		[AI2 Th Warning] (tP2A)		
27		[AI3 Th Warning] (tP3A)		
28		[AI4 Th Warning] (tP4A)		
29		[AI5 Th Warning] (tP5A)		
30		[AI1 4-20 Loss Warning] (AP1)		
31		[AI2 4-20 Loss Warning] (AP2)		
32		[AI3 4-20 Loss Warning] (AP3)		
33		[AI4 4-20 Loss Warning] (AP4)		
34		[AI5 4-20 Loss Warning] (AP5)		
35		[Drive Thermal Warning] (tHA)		
36		[IGBT Thermal Warning] (tJA)		
37		[Fan Counter Warning] (FCtA)		
38		[Fan Feedback Warning] (FFdA)		
40		[Ext. Error Warning] (EFA)		
41		[Undervoltage Warning] (USA)		
42		[Preventive UnderV Active] (UPA)		
44		[Mot Freq High Thd] (FtA)		
45		[Mot Freq Low Thd] (FtAL)		
46		[Mot Freq High Thd 2] (FqLA)		
47		[Mot Freq Low Thd 2] (F2AL)		
48		[High Speed Reached] (FLA)		
49		[Ref Freq High Thd reached] (rtAH)		

Code	Values	Display	Description
	50	[Ref Freq Low Thd reached] (rtAL)	
	51	[2nd Freq Thd Reached] (F2A)	
	52	[Current Thd Reached] (CtA)	
	53	[Low Current Reached] (CtAL)	
	56	[Process Undld Warning] (ULA)	
	57	[Process Overload Warning] (OLA)	
	60	[Drv Therm Thd reached] (tAd)	
	61	[Motor Therm Thd reached] (tSA)	
	65	[Power High Threshold] (PtHA)	
	66	[Power Low Threshold] (PtHL)	
	67	[Cust Warning 1] (CAS1)	
	68	[Cust Warning 2] (CAS2)	
	69	[Cust Warning 3] (CAS3)	
	70	[Cust Warning 4] (CAS4)	
	71	[Cust Warning 5] (CAS5)	
	73	[Power Cons Warning] (POWd)	
	74	[Switch OutPres Warning] (OPSA)	
	75	(InWM)	
APPS	0	[Running] (rUn)	
	1	[Stop] (StOP)	
	2	[Local Mode Active] (LOCAL)	
	3	[Channel 2 Active] (OUeR)	
	4	[Manual Mode Active] (MAnU)	
	5	[PID Active] (AUtO)	
	6	[Anti-Jam In progress] (AJAM)	
	7	[Flow limit In progress] (FLIM)	
	8	[PipeFill In progress] (FILL)	
	9	[Jockey Pump Active] (JOC EY)	
	10	[Boost In progress] (bOOSt)	
	11	[Sleep Active] (SLEEP)	
	12	[Priming Pump Active] (PrIM)	
	13	[InletPres Comp In progress] (COMP)	
AST	5	[PSI align.] (PSI)	
	6	[PSIO align.] (PSIO)	
	254	[No align.] (nO)	
AUT	0	[No] (nO)	
	1	[Yes] (YES)	
BDCO	38	[50 kbps] (50)	
	52	[125 kbps] (125)	
	60	[250 kbps] (250)	
	68	[500 kbps] (500)	
	76	[1 Mbps] (1M)	
BFR	0	[50Hz IEC] (50)	
	1	[60Hz NEMA] (60)	
BMP	0	[Stop] (StOP)	
	1	[Bumpless] (bUMP)	
	2	[Disabled] (dIS)	
BOA	0	[Inactive] (nO)	
	1	[Dynamic] (dYnA)	
	2	[Static] (StAt)	
	3	[Constant] (CStE)	
BRA	0	[No] (nO)	
	1	[Yes] (YES)	
	2	[High Torque] (dYnA)	
BSP	0	[Standard] (bSd)	
	1	[Deadband] (bLS)	
	2	[Pedestal] (bnS)	
	4	[Pedestal at 0%] (bnS0)	
CAR	0	[No Warning Clearing] (nO)	
	1	[Clear Event 1 Warning] (rA1)	
	2	[Clear Event 2 Warning] (rA2)	
	3	[Clear Event 3 Warning] (rA3)	
	4	[Clear Event 4 Warning] (rA4)	
	5	[Clear Event 5 Warning] (rA5)	
CCA	0	[Not Configured] (nO)	
	1	[Counter] (CPT)	
	2	[Date and Time] (dt)	
CCS	0	[Pwr/Control suppl ON] (0)	
	1	[Supply Mains ON] (1)	
	2	[Drv in run state] (2)	

Code	Values	Display	Description
CDX	1	[Terminals] (tEr)	
	3	[HMI] (LCC)	
	10	[Modbus] (Mdb)	
	20	[CANopen] (CAN)	
	30	[Com. Module] (nEt)	
	40	[Ethernet] (EtH)	
CFPS	0	[None] (nO)	
	1	[Set No.1] (CFP1)	
	2	[Set No.2] (CFP2)	
	3	[Set No.3] (CFP3)	
CHCF	1	[Not separ.] (SIM)	
	2	[Separate] (SEP)	
	3	[I/O profile] (IO)	
CINR	20	(0.001)	
	30	(0.01)	
	40	(0.1)	
	50	(1)	
	60	(10)	
CIOA	0	[20/70] (20)	
	1	[21/71] (21)	
	2	[100/101] (100)	
	3	[Unconfig.] (UnCG)	
CNFS	0	[In progress] (nO)	
	1	[Config. No.0] (CnF0)	
CNL	0	[Terminals] (tErM)	
	2	[HMI] (HMI)	
	3	[Modbus] (Mdb)	
	6	[CANopen] (CAN)	
	9	[Com. Module] (nEt)	
	11	[Ethernet Module] (EtH)	
COP	0	[No] (nO)	
	1	[Reference Frequency] (SP)	
	2	[Command] (Cd)	
	3	[Cmd + Ref Frequency] (ALL)	
CSLFN	0	[No] (nO)	
	181	[Preset Speed 1] (FPS1)	
	182	[Preset Speed 2] (FPS2)	
	183	[PID Ref Freq 1] (FPr1)	
	184	[PID Ref Freq 2] (FPr2)	
	185	[+speed] (FUSP)	
	186	[-speed] (FdSP)	
CSLOUT	0	[No] (nO)	
	146	[R2] (r2)	
	147	[R3] (r3)	
	148	[R4 Assignment] (r4)	
	149	[R5 Assignment] (r5)	
	150	[R6 Relay] (r6)	
	163	[DQ11 Digital Output] (dO11)	
	164	[DQ12 Digital Output] (dO12)	
	200	[VSP] (USP)	
CTT	3	[U/F VC Standard] (Std)	
	4	[U/F VC 5pts] (UF5)	
	6	[U/F VC Quad.] (UFq)	
	10	[SYN_U VC] (SYnU)	
	11	[U/F VC Energy Sav.] (ECO)	
DOTD	0	[Freewheel stop] (nSt)	
	1	[Ramp stop] (rMP)	
DPMA	1	[MCL1] (1)	
	2	[MCL2] (2)	
DRT	0	[Normal Duty] (nOrMAL)	
	1	[Heavy Duty] (HIGH)	
DRYM	0	[No] (nO)	
	1	[Switch] (SWt)	
	2	[Power] (PWt)	
DUR	0	[5 minutes] (5)	
	1	[10 minutes] (10)	
	2	[30 minutes] (30)	
	3	[1 hour] (1H)	
	4	[2 hours] (2H)	

Code	Values	Display	Description
	5	[3 hours] (3H)	
	6	[Unlimited] (Ct)	
ECFG	0	[Ignore] (nO)	
	1	[Freewheel Stop] (YES)	
	2	[Per STT] (Stt)	
	4	[Fallback Speed] (LFF)	
	5	[Speed maintained] (rLS)	
	6	[Ramp stop] (rMP)	
	7	[Fast stop] (FSt)	
	8	[DC injection] (dCI)	
ERRD	16#0000	[No Error] (nOF)	
	16#1000	[Precharge Capacitor] (CrF)	
	16#1000	[Motor Overspeed] (SOF)	
	16#1000	[Internal Error 14] (InFE)	
	16#1000	[Channel Switch Error] (CSF)	
	16#1000	[Angle error] (ASF)	
	16#2230	[IGBT Short Circuit] (SCF4)	
	16#2310	[Overcurrent] (OCF)	
	16#2311	[Process Overload] (OLC)	
	16#2320	[Motor short circuit] (SCF1)	
	16#2320	[Motor Short Circuit] (SCF5)	
	16#2330	[Ground Short Circuit] (SCF3)	
	16#2350	[Motor Overload] (OLF)	
	16#3110	[Supply Mains Overvoltage] (OSF)	
	16#3120	[Supply Mains UnderV] (USF)	
	16#3130	[Input phase loss] (PHF)	
	16#3300	[Single output phase loss] (OPF1)	
	16#3310	[DC Bus Overvoltage] (ObF)	
	16#3310	[Output Phase Loss] (OPF2)	
	16#4210	[Input Overheating] (IHF)	
	16#4210	[Drive Overheating] (OHF)	
	16#4210	[IGBT Overheating] (tJF)	
	16#4210	[AI2 Th Detected Error] (tH2F)	
	16#4210	[AI3 Th Detected Error] (tH3F)	
	16#4210	[AI4 Th Detected Error] (tH4F)	
	16#4210	[AI5 Th Detected Error] (tH5F)	
	16#5000	[Input Contactor] (LCF)	
	16#5100	[Internal Error 8] (InF8)	
	16#5100	[Internal Error 10] (InFA)	
	16#5210	[Internal Error 9] (InF9)	
	16#5210	[Internal Error 11] (InFb)	
	16#5210	[Internal Error 12] (InFC)	
	16#5210	[Internal Error 13] (InFd)	
	16#5500	[Internal Error 15] (InFF)	
	16#5530	[EEPROM Control] (EEF1)	
	16#5530	[EEPROM Power] (EEF2)	
	16#6100	[Internal Link Error] (ILF)	
	16#6100	[Internal Error 1] (InF1)	
	16#6100	[Internal Error 2] (InF2)	
	16#6100	[Internal Error 3] (InF3)	
	16#6100	[Internal Error 4] (InF4)	
	16#6100	[Internal Error 7] (InF7)	
	16#6100	[Internal Error 6] (InF6)	
	16#6100	[Boards Compatibility] (HCF)	
	16#6100	[Internal Error 0] (InF0)	
	16#6100	[Internal Error 21] (InFL)	
	16#6100	[Internal Error 22] (InFM)	
	16#6100	[Internal Error 25] (InFP)	
	16#6100	[Internal Error 20] (InF)	
	16#6100	[Internal Error 27] (InFr)	
	16#6300	[Incorrect Configuration] (CFF)	
	16#6300	[Invalid Configuration] (CFI)	
	16#6300	[Conf Transfer Error] (CFI2)	
16#7000	[Internal Error 16] (InFG)		
16#7000	[Internal Error 17] (InFH)		
16#7121	[Motor Stall Error] (StF)		
16#7300	[AI2 4-20mA loss] (LFF2)		
16#7300	[AI3 4-20mA loss] (LFF3)		
16#7300	[AI4 4-20mA loss] (LFF4)		
16#7300	[AI5 4-20 mA loss] (LFF5)		

Code	Values	Display	Description
	16#7300	[AI1 4-20 mA loss] (LFF1)	
	16#7300	[AI2 Thermal Sensor Error] (t2CF)	
	16#7300	[AI3 Thermal Sensor Error] (t3CF)	
	16#7300	[AI4 Thermal Sensor Error] (t4CF)	
	16#7300	[AI5 Thermal Sensor Error] (t5CF)	
	16#7400	[Program Loading Error] (PGLF)	
	16#7400	[Program Running Error] (PGrF)	
	16#7500	[PID Feedback Error] (PFMF)	
	16#7510	[Modbus Com Interruption] (SLF1)	
	16#7510	[HMI Com Interruption] (SLF3)	
	16#7520	[Fieldbus Com Interrupt] (CnF)	
	16#7530	[PC Com Interruption] (SLF2)	
	16#7540	[Embd Eth Com Interrupt] (EtHF)	
	16#8100	[CANopen Com Interrupt] (COF)	
	16#9000	[External Error] (EPF1)	
	16#9000	[Fieldbus Error] (EPF2)	
	16#FF00	[Autotuning Error] (tnF)	
	16#FF03	[Process Underload] (ULF)	
	16#FF03	[Safety Function Error] (SAFF)	
	16#FF11	[PumpCycle Start Error] (PCPF)	
	16#FF11	[Inlet Pressure Error] (IPPF)	
	16#FF11	[Pump Low Flow Error] (PLFF)	
	16#FF11	[Anti Jam Error] (JAMF)	
	16#FF11	[Dry Run Error] (drYF)	
	16#FF12	[Out Pressure Low] (OPLF)	
	16#FF12	[High Flow Error] (HFPF)	
	16#FF12	[Out Pressure High] (OPHF)	
FCS	0	(nO)	
	1	(rEC0)	
	2	(rEC1)	
	3	(rEC2)	
	4	(rEC3)	
	64	(InI)	
	71	(InI1)	
FEM	0	[No] (nO)	
	1	[HQ] (Hq)	
	2	[PQ] (Pq)	
FFM	0	[Standard] (Std)	
	1	[Always] (rUn)	
	2	[UnderV. prevention] (StP)	
	3	[Economy] (ECO)	
FLCM	0	[Inactive] (nO)	
	1	[Display] (MOn)	
	2	[Compensation] (COMP)	
FOR	2	[8-O-1] (8o1)	
	3	[8-E-1] (8E1)	
	4	[8-N-1] (8n1)	
	5	[8-N-2] (8n2)	
HMIS	0	[Autotuning] (tUn)	
	1	[In DC inject.] (dCb)	
	2	[Ready] (rdY)	
	3	[Freewheel] (nSt)	
	4	[Running] (rUn)	
	5	[Accelerating] (ACC)	
	6	[Decelating] (dEC)	
	7	[Current limitation] (CLI)	
	8	[Fast stop] (FSt)	
	9	[Mot. fluxing] (FLU)	
	11	[No Mains Voltage] (nLP)	
	13	[control.stop] (CtL)	
	14	[Dec. adapt.] (Obr)	
	15	[Output cut] (SOC)	
	17	[Undervoltage Warning] (USA)	
	18	[TC Mode Active] (tC)	
	19	[In autotest] (St)	
	20	[Autotest error] (FA)	
	21	[Autotest OK] (YES)	
	22	[EEprom test] (EP)	
	23	["Operating State ""Fault"" "] (FLt)	
	25	[DCP Flashing Mode] (dCP)	

Code	Values	Display	Description
	30	[STO active] (StO)	
	35	[Energy Saving] (IdLE)	
INR	0	[0.01] (0.01)	
	1	[0.1] (0.1)	
	2	[1] (1)	
IPPM	0	[No] (nO)	
	1	[Warning] (ALArM)	
	2	[Compensation] (COMP)	
JATC	0	[No] (nO)	
	1	[Start] (StArt)	
	2	[Time] (tIME)	
	3	[Torque] (tOrqUE)	
LDD	0	[Distrib. Log. DISABLE] (nO)	
	1	[Motor Frequency] (rFr)	
	2	[Motor Current] (LCr)	
	3	[Motor Speed] (SPd)	
	4	[Motor Voltage] (UOP)	
	5	[Motor Mech. Power] (OPrW)	
	6	[Input Elec. Power] (IPrW)	
	7	[Output Elec. Power] (EPrW)	
	8	[Motor Torque] (Otr)	
	9	[Mains Voltage] (ULn)	
	10	[DC BUS Voltage] (UbUS)	
	11	[PID feedback] (rPF)	
	12	[AI2 Th Value] (tH2U)	
	13	[AI3 Th Value] (tH3U)	
	14	[AI4 Th Value] (tH4U)	
	15	[AI5 Th Value] (tH5U)	
	16	[Drive Thermal State] (tHd)	
	17	[Motor Thermal State] (tHr)	
	18	[Installation Flow] (FS1U)	
	19	[Pump Flow] (FS2U)	
	20	[Inlet Pressure] (PS1U)	
	21	[Outlet Pressure] (PS2U)	
	22	[Energy Consum. Ind.] (ECI)	
	23	[Pump efficiency] (EFY)	
24	[Energy Perf. Ind.] (EPI)		
LDEN	0	[Stop] (StOP)	
	1	[Start] (StArt)	
	2	[Always] (ALWAYS)	
	3	[Reset] (rESEt)	
	4	[Clear] (CLEAr)	
	5	[Error] (ErrOr)	
LDST	2	[200 ms] (200MS)	
	10	[1 second] (1S)	
	20	[2 seconds] (2S)	
	50	[5 seconds] (5S)	
LFT	0	[No Error] (nOF)	
	2	[EEPROM Control] (EEF1)	
	3	[Incorrect Configuration] (CFF)	
	4	[Invalid Configuration] (CFI)	
	5	[Modbus Com Interruption] (SLF1)	
	6	[Internal Link Error] (ILF)	
	7	[Fieldbus Com Interrupt] (CnF)	
	8	[External Error] (EPF1)	
	9	[Overcurrent] (OCF)	
	10	[Precharge Capacitor] (CrF)	
	13	[AI2 4-20mA loss] (LFF2)	
	15	[Input Overheating] (IHF)	
	16	[Drive Overheating] (OHF)	
	17	[Motor Overload] (OLF)	
	18	[DC Bus Overvoltage] (ObF)	
	19	[Supply Mains Overvoltage] (OSF)	
	20	[Single output phase loss] (OPF1)	
	21	[Input phase loss] (PHF)	
	22	[Supply Mains UnderV] (USF)	
	23	[Motor short circuit] (SCF1)	
	24	[Motor Overspeed] (SOF)	
	25	[Autotuning Error] (tnF)	
	26	[Internal Error 1] (InF1)	

Code	Values	Display	Description
	27	[Internal Error 2] (InF2)	
	28	[Internal Error 3] (InF3)	
	29	[Internal Error 4] (InF4)	
	30	[EEPROM Power] (EEF2)	
	32	[Ground Short Circuit] (SCF3)	
	33	[Output Phase Loss] (OPF2)	
	34	[CANopen Com Interrupt] (COF)	
	37	[Internal Error 7] (InF7)	
	38	[Fieldbus Error] (EPF2)	
	40	[Internal Error 8] (InF8)	
	42	[PC Com Interruption] (SLF2)	
	45	[HMI Com Interruption] (SLF3)	
	51	[Internal Error 9] (InF9)	
	52	[Internal Error 10] (InFA)	
	53	[Internal Error 11] (InFb)	
	54	[IGBT Overheating] (tJF)	
	55	[IGBT Short Circuit] (SCF4)	
	56	[Motor Short Circuit] (SCF5)	
	60	[Internal Error 12] (InFC)	
	64	[Input Contactor] (LCF)	
	68	[Internal Error 6] (InF6)	
	69	[Internal Error 14] (InFE)	
	71	[AI3 4-20mA loss] (LFF3)	
	72	[AI4 4-20mA loss] (LFF4)	
	73	[Boards Compatibility] (HCF)	
	77	[Conf Transfer Error] (CFI2)	
	79	[AI5 4-20 mA loss] (LFF5)	
	99	[Channel Switch Error] (CSF)	
	100	[Process Underload] (ULF)	
	101	[Process Overload] (OLC)	
	105	[Angle error] (ASF)	
	106	[AI1 4-20 mA loss] (LFF1)	
	107	[Safety Function Error] (SAFF)	
	110	[AI2 Th Detected Error] (tH2F)	
	111	[AI2 Thermal Sensor Error] (t2CF)	
	112	[AI3 Th Detected Error] (tH3F)	
	113	[AI3 Thermal Sensor Error] (t3CF)	
	114	[PumpCycle Start Error] (PCPF)	
	115	[Out Pressure Low] (OPLF)	
	116	[High Flow Error] (HFPP)	
	117	[Inlet Pressure Error] (IPPF)	
	119	[Pump Low Flow Error] (PLFF)	
	120	[AI4 Th Detected Error] (tH4F)	
	121	[AI4 Thermal Sensor Error] (t4CF)	
	122	[AI5 Th Detected Error] (tH5F)	
	123	[AI5 Thermal Sensor Error] (t5CF)	
	124	[Anti Jam Error] (JAMF)	
	125	[Out Pressure High] (OPHF)	
	126	[Dry Run Error] (drYF)	
	127	[PID Feedback Error] (PFMF)	
	128	[Program Loading Error] (PGLF)	
	129	[Program Running Error] (PGrF)	
	142	[Internal Error 16] (InFG)	
	143	[Internal Error 17] (InFH)	
	144	[Internal Error 0] (InF0)	
	146	[Internal Error 13] (InFd)	
	148	[Motor Stall Error] (StF)	
	149	[Internal Error 21] (InFL)	
	150	[Embd Eth Com Interrupt] (EthF)	
	151	[Internal Error 15] (InFF)	
	153	[Internal Error 22] (InFM)	
	154	[Internal Error 25] (InFP)	
	155	[Internal Error 20] (InF)	
	157	[Internal Error 27] (InFr)	
N_Y	0	[No] (nO)	
	1	[Yes] (YES)	
NCV	0	[Unknown rating] (nO)	
	1	[0.12kW] (U01)	
	2	[0.18kW / 0.25Hp] (U02)	
	3	[0.25kW] (U03)	

Code	Values	Display	Description
	4	[0.37 kW / 0.5 Hp] (U04)	
	5	[0.55 kW / 0.75 Hp] (U05)	
	6	[0.75 kW / 1 Hp] (U07)	
	7	[5.5kW / 7.5HP] (U09)	
	8	[1.1 kW / 1.5 Hp] (U11)	
	9	[1.5 kW / 2 Hp] (U15)	
	10	[1.85kW] (U18)	
	11	[2.2 kW / 3 Hp] (U22)	
	12	[3 kW / -] (U30)	
	13	[4kW / 5HP] (U37)	
	14	[4kW / 5HP] (U40)	
	15	[5.5 kW / 7.5 Hp] (U55)	
	16	[7.5 kW / 10 Hp] (U75)	
	17	[9kW] (U90)	
	18	[11 kW / 15 Hp] (d11)	
	19	[15 kW / 20 Hp] (d15)	
	20	[18,5kW / 25HP] (d18)	
	21	[22kW / 30HP] (d22)	
	22	[30kW / 40HP] (d30)	
	23	[37kW / 50HP] (d37)	
	24	[45kW / 60HP] (d45)	
	25	[55kW / 75HP] (d55)	
	26	[75kW / 100HP] (d75)	
	27	[90kW / 125HP] (d90)	
	28	[110 kW / 150HP] (C11)	
	29	[132kW / 200 HP] (C13)	
	30	[160kW / 250HP] (C16)	
	31	[200kW / 300HP] (C20)	
	32	[220kW / 350HP] (C22)	
	33	[250kW / 400HP] (C25)	
	34	[280kW / 450HP] (C28)	
	35	[315kW / 500HP] (C31)	
	36	[355 kW] (C35)	
	37	[400kW / 600HP] (C40)	
	38	[450kW] (C45)	
	39	[500kW / 700HP] (C50)	
	40	[560kW] (C56)	
	41	[630kW] (C63)	
	42	[710kW] (C71)	
	43	[800kW] (C80)	
NPL	0	[1] (POS)	
	1	[0] (nEG)	
OPL	0	[Function Inactive] (nO)	
	1	[OPF Error Triggered] (YES)	
	2	[No Error Triggered] (OAC)	
OPPM	0	[No] (nO)	
	1	[Switch] (SW)	
	2	[Sensor] (SnSr)	
	3	[Both] (bOtH)	
PCM	0	[No] (nO)	
	1	[HQ] (Hq)	
	2	[PQ] (Pq)	
	3	[PHQ] (PHq)	
PCPM	0	[No] (nO)	
	1	[Mode 1] (nOrM)	
	2	[Mode 2] (rtC)	
PCS	0	[None] (nOnE)	
	1	[Inactive] (nACT)	
	2	[Active] (ACTIUE)	
	3	[Failed] (FAILED)	
PFM	0	[No] (nO)	
	1	[Horizontal] (HOr)	
PHR	0	[ABC] (AbC)	
	1	[ACB] (ACb)	
PLFM	0	[No] (nO)	
	1	[Switch] (SW)	
	2	[Flow] (q)	
	3	[Flow vs Speed] (qn)	
	5	[No Flow Power] (nF)	
PRFL	0	(UnCG)	

Code	Values	Display	Description
	1	(1)	
	100	(100)	
	101	(101)	
	102	(102)	
	106	(106)	
	107	(107)	
PSA	0	[Not Configured] (nO)	
	1	[AI1] (AI1)	
	2	[AI2] (AI2)	
	3	[AI3] (AI3)	
	4	[AI4] (AI4)	
	5	[AI5] (AI5)	
	129	[Motor Current] (OCr)	
	130	[Motor Frequency] (OFr)	
	131	[Ramp out.] (OrP)	
	132	[Motor torq.] (trq)	
	133	[Sign. torque] (Stq)	
	134	[sign ramp] (OrS)	
	135	[PID ref.] (OPS)	
	136	[PID feedbk] (OPF)	
	137	[PID error] (OPE)	
	138	[PID output] (OPI)	
	139	[Drive Power] (OPr)	
	140	[Mot thermal] (tHr)	
	141	[Drv thermal] (tHd)	
	160	[Ref Frequency via DI] (UPdt)	
	163	[Ref.Freq-Rmt.Term] (LCC)	
	164	[Ref. Freq-Modbus] (Mdb)	
	167	[Ref. Freq-CANopen] (CAn)	
	169	[Ref. Freq-Com. Module] (nEt)	
	171	[Embedded Ethernet] (EtH)	
	173	[Sig. o/p frq.] (OFS)	
	180	[Motor volt.] (UOP)	
	183	[AI Virtual 1] (AIU1)	
	186	[DI5 PulseInput Assignment] (PI5)	
	187	[DI6 PulseInput Assignment] (PI6)	
	340	[Flow Estimation] (SLPF)	
	341	[Inlet Pressure Value] (PS1U)	
342	[Outlet Pressure Value] (PS2U)		
343	[Installation Flow] (FS1U)		
PSL	0	[Not Assigned] (nO)	
	1	[Operating State Fault] (FLt)	
	2	[Drive Running] (rUn)	
	4	[Mot Freq High Thd] (FtA)	
	5	[High Speed Reached] (FLA)	
	6	[Current Thd Reached] (CtA)	
	7	[Ref Freq Reached] (SrA)	
	8	[Motor Therm Thd reached] (tSA)	
	10	[PID error Warning] (PEE)	
	11	[PID feedback Warning] (PFA)	
	12	[AI2 4-20 Loss Warning] (AP2)	
	13	[2nd Freq Thd Reached] (F2A)	
	14	[Drv Therm Thd reached] (tAd)	
	16	[Ref Freq High Thd reached] (rtAH)	
	17	[Ref Freq Low Thd reached] (rtAL)	
	18	[Mot Freq Low Thd] (FtAL)	
	19	[Mot Freq Low Thd 2] (F2AL)	
	20	[Low Current Reached] (CtAL)	
	21	[Process Undld Warning] (ULA)	
	22	[Process Overload Warning] (OLA)	
	23	[PID High Fdbck Warning] (PFAH)	
	24	[PID Low Fdbck Warning] (PFAL)	
	25	[Regulation Warning] (PISH)	
	28	[High Torque Warning] (ttHA)	
	29	[Low Torque Warning] (ttLA)	
	30	[Forward] (MFrd)	
	31	[Reverse] (MrrS)	
	34	[Ramp switching] (rP2)	
	47	[Neg Torque] (AtS)	
	48	[Cnfg.0 act.] (CnF0)	

Code	Values	Display	Description
	52	[set 1 active] (CFP1)	
	53	[set 2 active] (CFP2)	
	54	[set 3 active] (CFP3)	
	55	[set 4 active] (CFP4)	
	64	[DC charged] (dbL)	
	66	[Power Removal State] (PrM)	
	72	[Mot Freq High Thd 2] (FqLA)	
	73	[Mains Contactor] (LLC)	
	77	[I present] (MCP)	
	80	[Warning Grp 1] (AG1)	
	81	[Warning Grp 2] (AG2)	
	82	[Warning Grp 3] (AG3)	
	87	[External Error Warning] (EFA)	
	88	[Undervoltage Warning] (USA)	
	89	[Preventive UnderV Active] (UPA)	
	91	[Drive Thermal Warning] (tHA)	
	96	[Ref Freq Channel 1] (Fr1)	
	97	[Ref Freq Channel 2] (Fr2)	
	98	[Cmd Channel 1] (Cd1)	
	99	[Cmd Channel 2] (Cd2)	
	100	[ch1B active] (Fr1b)	
	104	[IGBT Thermal Warning] (tJA)	
	107	[AI3 4-20 Loss Warning] (AP3)	
	108	[AI4 4-20 Loss Warning] (AP4)	
	110	[Flow Limit Active] (FSA)	
	116	[Function key 1] (Fn1)	
	117	[Function key 2] (Fn2)	
	118	[Function key 3] (Fn3)	
	119	[Function key 4] (Fn4)	
	123	[AI1 4-20 Loss Warning] (AP1)	
	127	[Ready] (rdY)	
	128	[Yes] (YES)	
	129	[DI1] (LI1)	
	130	[DI2] (LI2)	
	131	[DI3] (LI3)	
	132	[DI4] (LI4)	
	133	[DI5] (LI5)	
	134	[DI6] (LI6)	
	139	[DI11] (LI11)	
	140	[DI12] (LI12)	
	141	[DI13] (LI13)	
	142	[DI14] (LI14)	
	143	[DI15] (LI15)	
	144	[DI16] (LI16)	
	160	[CD00] (Cd00)	
	161	[CD01] (Cd01)	
	162	[CD02] (Cd02)	
	163	[CD03] (Cd03)	
	164	[CD04] (Cd04)	
	165	[CD05] (Cd05)	
	166	[CD06] (Cd06)	
	167	[CD07] (Cd07)	
	168	[CD08] (Cd08)	
	169	[CD09] (Cd09)	
	170	[CD10] (Cd10)	
	171	[CD11] (Cd11)	
	172	[CD 12] (Cd12)	
	173	[CD 13] (Cd13)	
	174	[CD14] (Cd14)	
	175	[CD15] (Cd15)	
	176	[C100] (C100)	
	177	[C101] (C101)	
	178	[C102] (C102)	
	179	[C103] (C103)	
	180	[C104] (C104)	
	181	[C105] (C105)	
	182	[C106] (C106)	
	183	[C107] (C107)	
	184	[C108] (C108)	
	185	[C109] (C109)	

Code	Values	Display	Description
	186	[C110] (C110)	
	187	[C111] (C111)	
	188	[C112] (C112)	
	189	[C113] (C113)	
	190	[C114] (C114)	
	191	[C115] (C115)	
	192	[C200] (C200)	
	193	[C201] (C201)	
	194	[C202] (C202)	
	195	[C203] (C203)	
	196	[C204] (C204)	
	197	[C205] (C205)	
	198	[C206] (C206)	
	199	[C207] (C207)	
	200	[C208] (C208)	
	201	[C209] (C209)	
	202	[C210] (C210)	
	203	[C211] (C211)	
	204	[C212] (C212)	
	205	[C213] (C213)	
	206	[C214] (C214)	
	207	[C215] (C215)	
	208	[C300] (C300)	
	209	[C301] (C301)	
	210	[C302] (C302)	
	211	[C303] (C303)	
	212	[C304] (C304)	
	213	[C305] (C305)	
	214	[C306] (C306)	
	215	[C307] (C307)	
	216	[C308] (C308)	
	217	[C309] (C309)	
	218	[C310] (C310)	
	219	[C311] (C311)	
	220	[C312] (C312)	
	221	[C313] (C313)	
	222	[C314] (C314)	
	223	[C315] (C315)	
	240	[Virtual DI CMD5.0] (C500)	
	241	[Virtual DI CMD5.1] (C501)	
	242	[Virtual DI CMD5.2] (C502)	
	243	[Virtual DI CMD5.3] (C503)	
	244	[Virtual DI CMD5.4] (C504)	
	245	[Virtual DI CMD5.5] (C505)	
	246	[Virtual DI CMD5.6] (C506)	
	247	[Virtual DI CMD5.7] (C507)	
	248	[Virtual DI CMD5.8] (C508)	
	249	[Virtual DI CMD5.9] (C509)	
	250	[Virtual DI CMD5.10] (C510)	
	251	[Virtual DI CMD5.11] (C511)	
	252	[Virtual DI CMD5.12] (C512)	
	253	[Virtual DI CMD5.13] (C513)	
	254	[Virtual DI CMD5.14] (C514)	
	255	[Virtual DI CMD5.15] (C515)	
	272	[DI1 (Low level)] (L1L)	
	273	[DI2 (Low level)] (L2L)	
	274	[DI3 (Low level)] (L3L)	
	275	[DI4 (Low level)] (L4L)	
	276	[DI5 (Low level)] (L5L)	
	277	[DI6 (Low level)] (L6L)	
	282	[DI11 (Low level)] (L11L)	
	283	[DI12 (Low level)] (L12L)	
	284	[DI13 (Low level)] (L13L)	
	285	[DI14 (Low level)] (L14L)	
	286	[DI15 (Low level)] (L15L)	
	287	[DI16 (Low level)] (L16L)	
	340	[Jockey] (JO Y)	
	341	[Priming] (PRIM)	
	342	[Anti-Jam Active] (JAMr)	
	344	[Pipe Fill] (FILL)	

Code	Values	Display	Description
	345	[Priming Pump Active] (PPOn)	
	346	[Drive Running Warning] (drYA)	
	347	[Pump Low Flow] (PLFA)	
	348	[Proc High Flow Warning] (HFPA)	
	349	[Mot Freq Low Thd] (IPPA)	
	350	[Low OutPres Warning] (OPLA)	
	351	[High OutPres Warning] (OPHA)	
	352	[Pump Cycle Warning] (PCPA)	
	353	[Anti-Jam Warning] (JAMA)	
	354	[Low Flow Warning] (LFA)	
	355	[Low Pressure Warning] (LPA)	
	356	[Switch OutPres Warning] (OPSA)	
	357	[Jockey Pump Active] (JPOn)	
	491	[Power Cons Warning] (POWd)	
	492	[Warning Grp 4] (AG4)	
	493	[Warning Grp 5] (AG5)	
	494	[Fallback speed] (FrF)	
	495	[Speed Maintained] (rLS)	
	496	[Per Type of Stop] (Stt)	
	497	[Life Cycle Warn 1] (LCA1)	
	498	[Life Cycle Warn 2] (LCA2)	
	499	[AI2 Th Warning] (tP2A)	
	500	[AI3 Th Warning] (tP3A)	
	501	[AI4 Th Warning] (tP4A)	
	502	[AI5 Th Warning] (tP5A)	
	503	[AI5 4-20 Loss Warning] (AP5)	
	504	[Fan Counter Warning] (FCtA)	
	505	[Fan Feedback Warning] (FFdA)	
	506	[Power High Threshold] (PtHA)	
	507	[Power Low Threshold] (PtHL)	
	508	[Cust Warning 1] (CAS1)	
	509	[Cust Warning 2] (CAS2)	
	510	[Cust Warning 3] (CAS3)	
	511	[Cust Warning 4] (CAS4)	
PSLIN	0	[Not Assigned] (nO)	
	1	[Operating State Fault] (FLt)	
	4	[Mot Freq High Thd] (FtA)	
	13	[2nd Freq Thd Reached] (F2A)	
	18	[Mot Freq Low Thd] (FtAL)	
	19	[Mot Freq Low Thd 2] (F2AL)	
	96	[Ref Freq Channel 1] (Fr1)	
	97	[Ref Freq Channel 2] (Fr2)	
	98	[Cmd Channel 1] (Cd1)	
	99	[Cmd Channel 2] (Cd2)	
	100	[ch1B active] (Fr1b)	
	128	[Yes] (YES)	
	129	[DI1] (LI1)	
	130	[DI2] (LI2)	
	131	[DI3] (LI3)	
	132	[DI4] (LI4)	
	133	[DI5] (LI5)	
	134	[DI6] (LI6)	
	139	[DI11] (LI11)	
	140	[DI12] (LI12)	
	141	[DI13] (LI13)	
	142	[DI14] (LI14)	
	143	[DI15] (LI15)	
	144	[DI16] (LI16)	
	160	[CD00] (Cd00)	
	161	[CD01] (Cd01)	
	162	[CD02] (Cd02)	
	163	[CD03] (Cd03)	
	164	[CD04] (Cd04)	
	165	[CD05] (Cd05)	
	166	[CD06] (Cd06)	
	167	[CD07] (Cd07)	
	168	[CD08] (Cd08)	
	169	[CD09] (Cd09)	
170	[CD10] (Cd10)		
171	[CD11] (Cd11)		

Code	Values	Display	Description
	172	[CD 12] (Cd12)	
	173	[CD 13] (Cd13)	
	174	[CD14] (Cd14)	
	175	[CD15] (Cd15)	
	177	[C101] (C101)	
	178	[C102] (C102)	
	179	[C103] (C103)	
	180	[C104] (C104)	
	181	[C105] (C105)	
	182	[C106] (C106)	
	183	[C107] (C107)	
	184	[C108] (C108)	
	185	[C109] (C109)	
	186	[C110] (C110)	
	187	[C111] (C111)	
	188	[C112] (C112)	
	189	[C113] (C113)	
	190	[C114] (C114)	
	191	[C115] (C115)	
	193	[C201] (C201)	
	194	[C202] (C202)	
	195	[C203] (C203)	
	196	[C204] (C204)	
	197	[C205] (C205)	
	198	[C206] (C206)	
	199	[C207] (C207)	
	200	[C208] (C208)	
	201	[C209] (C209)	
	202	[C210] (C210)	
	203	[C211] (C211)	
	204	[C212] (C212)	
	205	[C213] (C213)	
	206	[C214] (C214)	
	207	[C215] (C215)	
	209	[C301] (C301)	
	210	[C302] (C302)	
	211	[C303] (C303)	
	212	[C304] (C304)	
	213	[C305] (C305)	
	214	[C306] (C306)	
	215	[C307] (C307)	
	216	[C308] (C308)	
	217	[C309] (C309)	
	218	[C310] (C310)	
	219	[C311] (C311)	
	220	[C312] (C312)	
	221	[C313] (C313)	
	222	[C314] (C314)	
	223	[C315] (C315)	
	241	[Virtual DI CMD5.1] (C501)	
	242	[Virtual DI CMD5.2] (C502)	
	243	[Virtual DI CMD5.3] (C503)	
	244	[Virtual DI CMD5.4] (C504)	
	245	[Virtual DI CMD5.5] (C505)	
	246	[Virtual DI CMD5.6] (C506)	
	247	[Virtual DI CMD5.7] (C507)	
	248	[Virtual DI CMD5.8] (C508)	
	249	[Virtual DI CMD5.9] (C509)	
	250	[Virtual DI CMD5.10] (C510)	
	251	[Virtual DI CMD5.11] (C511)	
	252	[Virtual DI CMD5.12] (C512)	
	253	[Virtual DI CMD5.13] (C513)	
	254	[Virtual DI CMD5.14] (C514)	
	255	[Virtual DI CMD5.15] (C515)	
	272	[DI1 (Low level)] (L1L)	
	273	[DI2 (Low level)] (L2L)	
	274	[DI3 (Low level)] (L3L)	
	275	[DI4 (Low level)] (L4L)	
	276	[DI5 (Low level)] (L5L)	
	277	[DI6 (Low level)] (L6L)	

Code	Values	Display	Description
	282	[DI11 (Low level)] (L11L)	
	283	[DI12 (Low level)] (L12L)	
	284	[DI13 (Low level)] (L13L)	
	285	[DI14 (Low level)] (L14L)	
	286	[DI15 (Low level)] (L15L)	
	287	[DI16 (Low level)] (L16L)	
QSTD	2	(FSt2)	
	6	(FSt6)	
RDS	0	[Auto] (AUtO)	
	1	[10M. full] (10F)	
	2	[10M. half] (10H)	
	3	[100M. full] (100F)	
	4	[100M. half] (100H)	
RPR	0	[No] (nO)	
	2	[Run Time Reset] (rtH)	
	3	[Internal Run Time Reset] (rtHI)	
	4	[Power ON Time Reset] (PtH)	
	7	[Reset Fan Counter] (FtH)	
	8	[In Power ON Time Reset] (PtHI)	
	9	[Clear GtHI] (GtHI)	
	10	[Clear LtHI] (LtHI)	
	11	[Clear nSM] (nSM)	
	12	[Clear nSMI] (nSMI)	
	20	[Efficiency MAX] (EFY)	
	21	[Efficiency MIN] (EFYJ)	
	22	[Flow Rate MAX] (FS1)	
	23	[Flow Rate MIN] (FS1J)	
	24	[Reset Total Quantity] (FS1C)	
	64	[Reset all] (ALL)	
RPT	0	[Linear] (LIn)	
	1	[S-Ramp] (S)	
	2	[U-Ramp] (U)	
	3	[Customized] (CUS)	
SCS	0	[No] (nO)	
	1	[Config 0] (Str0)	
	2	[Save Config 1] (Str1)	
	3	[Config 2] (Str2)	
	4	[Config 3] (Str3)	
SFT	1	[SFR type 1] (HF1)	
	2	[SFR type 2] (HF2)	
SLPM	0	[No] (nO)	
	1	[Switch] (SW)	
	2	[Flow] (LF)	
	3	[Speed] (SPd)	
	4	[Power] (PWr)	
	5	[Pressure] (HP)	
	6	[Multiple] (Or)	
SMOT	0	[No info.] (nO)	
	1	[Low salient] (LLS)	
	2	[Med salient] (MLS)	
	3	[High salient] (HLS)	
SOP	6	[6] (6)	
	8	[8] (8)	
	10	[10] (10)	
STOS	0	[Not active] (IdLE)	
	1	[Active] (StO)	
	2	[Error] (FLt)	
STP	0	[Inactive] (nO)	
	1	[Maintain DC Bus] (MMS)	
	2	[Ramp Stop] (rMP)	
	4	[Freewheel Stop] (LnF)	
STR	0	[No Save] (nO)	
	1	[Save to RAM] (rAM)	
	2	[Save to EEPROM] (EEP)	
STT	0	[On Ramp] (rMP)	
	1	[Fast stop] (FSt)	
	2	[Freewheel Stop] (nSt)	
	3	[DC injection] (dCl)	
STUN	0	[Default] (tAb)	

Code	Values	Display	Description
	1	[Measure] (MEAS)	
	2	[Custom] (CUS)	
SUCU	0	[Euro] (EUrO)	
	1	[\$] (dOLLAr)	
	2	[£] (POUnd)	
	3	[Krone] (r)	
	4	[Renminbi] (rMb)	
	5	[Other] (OtHEr)	
SUFR	0	[1 L/s] (1LS)	
	1	[0.1 l/s] (01LS)	
	2	[1 L/m] (1LM)	
	3	[1 L/h] (1LH)	
	4	[1 dm3/mn] (1dM3M)	
	5	[1 m3/s] (1M3S)	
	6	[0.1 m3/s] (01M3S)	
	7	[1 m3/m] (1M3Mn)	
	8	[0.1 m3/m] (01M3Mn)	
	9	[1 m3/h] (1M3H)	
	10	[0.1 m3/h] (01M3H)	
	11	[1 gal/s] (1GPS)	
	12	[1 GPM] (1GPM)	
	13	[1 gal/h] (1GPH)	
	14	[1 ft3/s] (1CFS)	
	15	[1 CFM] (1CFM)	
	16	[1 SCFM] (1SCFM)	
	17	[1 ft3/h] (1CFH)	
	18	[1 Kg/s] (1 GS)	
	19	[1 Kg/m] (1 GM)	
	20	[1 Kg/h] (1 GH)	
	21	[1 Lb/s] (1LbS)	
	22	[1 Lb/m] (1LbM)	
	23	[1 Lb/h] (1LbH)	
	24	[0.1 %] (01PC)	
25	[0.1] (01WO)		
SUPR	0	[1 Kpa] (1 PA)	
	1	[1 mbar] (1Mbar)	
	2	[1 Bar] (1bAr)	
	3	[0.1 Bar] (01bAr)	
	4	[0.01 Bar] (001bAr)	
	5	[1 Psi] (1PSI)	
	6	[0.1 Psi] (01PSI)	
	7	[1 Psig] (1PSIG)	
	8	[0.1 Psig] (01PSIG)	
	9	[1 inH2O] (1InH2O)	
	10	[1 inWg] (1InWG)	
	11	[1 inWC] (1InWC)	
	12	[1 ftWg] (1FtWG)	
	13	[1 ftWc] (1FtWC)	
	14	[1 ft] (1Ft)	
	15	[1 mWg] (1MWG)	
	16	[0.1 mWg] (01MWG)	
	17	[1 mWC] (1MWC)	
	18	[0.1 mWc] (01MWC)	
	19	[1 m] (1M)	
	20	[0.1 m] (01M)	
	21	[1 inHg] (1InHG)	
	22	[0.1 %] (01PC)	
23	[0.1] (01WO)		
SUTP	0	[0.1°C] (01C)	
	1	[0.1°F] (01F)	
	2	[0.1 %] (01PC)	
	3	[0.1] (01WO)	
TBR	4	[Automatic] (AUtO)	
	8	[300 bps] (300)	
	12	[600 bps] (600)	
	16	[1.2 Kbps] (1 2)	
	20	[2.4 Kbps] (2 4)	
	24	[4800 bps] (4 8)	
	28	[9600 bps] (9 6)	
30	[10 Kbps] (10)		

Code	Values	Display	Description
	32	[19200 bps] (19 2)	
	34	[20 Kbps] (20)	
	35	[28.8 Kbps] (28 8)	
	36	[38.4 Kbps] (38 4)	
	37	[45.45 Kbps] (45 4)	
	38	[50 Kbps] (50)	
	40	[57.6 Kbps] (57 6)	
	42	[93.75 Kbps] (93 7)	
	44	[100 Kbps] (100)	
	48	[115.2 Kbps] (115)	
	52	[125 Kbps] (125)	
	53	[156 Kbps] (156)	
	54	[187.5 Kbps] (187)	
	56	[230.4 Kbps] (230)	
	60	[250 Kbps] (250)	
	64	[460.8 Kbps] (460)	
	68	[500 Kbps] (500)	
	69	[625 Kbps] (625)	
	70	[800 Kbps] (800)	
	72	[921.6 Kbps] (921)	
	76	[1 Mbps] (1M)	
	80	[1.5 Mbps] (1M5)	
	81	[2.5 Mbps] (2M5)	
	82	[3 Mbps] (3M)	
	83	[6 Mbps] (6M)	
	84	[10 Mbps] (10M)	
	86	[5 Mbps] (5M)	
	88	[12 Mbps] (12M)	
	92	[100 Mbps] (100M)	
TCC	0	[2-Wire Control] (2C)	
	1	[3-Wire Control] (3C)	
TCT	0	[Level] (LEL)	
	1	[Transition] (trn)	
	2	[Level With Fwd Priority] (PFO)	
THT	0	[No] (nO)	
	1	[Self cooled] (ACL)	
	2	[Force-cool] (FCL)	
TOCT	0	[NA] (nA)	
	1	[PRESSURE] (PrESS)	
	2	[FLOW] (FLOW)	
	3	[OTHER] (OtHER)	
URES	20	[200 Vac] (200)	
	22	[220 Vac] (220)	
	23	[230 Vac] (230)	
	24	[240 Vac] (240)	
	38	[380 Vac] (380)	
	40	[400 Vac] (400)	
	44	[440 Vac] (440)	
	46	[460 Vac] (460)	
	48	[480 Vac] (480)	
	52	[525V ac] (525)	
	57	[575 Vac] (575)	
	60	[600 Vac] (600)	
	69	[690 Vac] (690)	
USB	0	[Error Triggered] (0)	
	1	[Error Triggered w/o Relay] (1)	
	2	[Warning Triggered] (2)	
VCAL	0	[Unknown Voltage] (nO)	
	1	[100-120(1)] (110M)	
	2	[100-120(3)] (110t)	
	3	[200-240 V single] (M2)	
	4	[200-240 V Three] (M3)	
	5	[380-500(1)] (480M)	
	6	[380-500 V Three] (n4)	
	7	[525-600(1)] (690M)	
	8	[525-600 V Three] (S6)	
WUPM	0	[FeedBack] (Fb)	
	1	[Error] (Err)	
	2	[Pressure] (LP)	

CCC CRC	<p>Bit 0: = 1 : Terminal board Bit 1: = 1 : Local keypad Bit 2: = 1 : Deported keypad Bit 3: = 1 : Deported keypad</p> <p>Bit 4: Reserved (= 0). Bit 5: Reserved (= 0). Bit 6: = 1 : CANopen Bit 7: = 1 : Terminal up-Down speed</p> <p>Bit 8: = 1 : Deported keypad up-down speed Bit 9: = 1 : COM option board Bit 10: = 1 : APP option board Bit 11: = 1 : Embedded Ethernet</p> <p>Bit 12: Reserved (= 0). Bit 13: Reserved (= 0). Bit 14: Reserved (= 0). Bit 15: = 1: SoMove software is the active channel.</p>
CIC	<p>Bit 0: = 1: Change of rating. Bit 1: Reserved (= 0). Bit 2: = 1: The network card has been removed. Bit 3: = 1: Saving to the EEPROM non-volatile memory is inconsistent with power on.</p> <p>Bit 4: = 1: The network card has been changed. Bit 5: Reserved (= 0). Bit 6: Reserved (= 0). Bit 7: Reserved (= 0).</p> <p>Bit 8: Reserved (= 0). Bit 9: Reserved (= 0). Bit 10: Reserved (= 0). Bit 11: Reserved (= 0).</p> <p>Bit 12: Reserved (= 0). Bit 13: Reserved (= 0). Bit 14: Reserved (= 0). Bit 15: Reserved (= 0).</p> <p>If one of these events occurs, the drive will indicate a fault [Invalid config.] (CFI) and then automatically applies a factory setting.</p>
CMD CMP0 CMP1 CMP2 CMP3 CMP4 CMP5 CMP6 CMP7 CMP8 CMPA CMPB CMPC CMPD CMPE CMPF	<p>Possible values in CiA402 profile, separate or not separate mode:</p> <p>Bit 0: Switch on/Contactor command. Bit 1: Disable voltage/Authorization to supply AC power. Bit 2: Quick stop/Emergency stop. Bit 3: Enable operation/Run command.</p> <p>Bit 4: Reserved (set to 0). Bit 5: Reserved (set to 0). Bit 6: Reserved (set to 0). Bit 7: Fault reset/Fault acknowledgment active on 0 to 1 rising edge.</p> <p>Bit 8: Halt Stop according to the [Type of stop] (Stt) parameter without leaving the Operation enabled state. Bit 9: Reserved (set to 0). Bit 10: Reserved (set to 0). Bit 11: Can be assigned to commands.</p> <p>Bit 12: Can be assigned to commands. Bit 13: Can be assigned to commands. Bit 14: Can be assigned to commands. Bit 15: Can be assigned to commands.</p> <p>Possible values in the IO profile: On state command [2 wire] (2C). Bit 0: Forward (on state) command = 0: No forward command = 1: Forward command</p> <p>The assignment of Bit 0 cannot be modified. It corresponds to the assignment of the terminals. It can be switched. Bit 0 (Cd00) is only active if the channel of this control word is active. Bit 1 to Bit 15: Can be assigned to commands.</p> <p>On edge command [3 wire] (3C).</p>

	<p>Bit 0: Stop (run authorization). = 0: Stop = 1: Run is authorized on a forward or reverse command</p> <p>Bit 1: Forward (on 0 to 1 rising edge) command.</p> <p>The assignment of Bits 0 and 1 cannot be modified. It corresponds to the assignment of the terminals. It can be switched. Bits 0 (Cd00) and 1 (Cd01) are only active if the channel of this control word is active.</p> <p>Bit 2 to Bit 15 can be assigned to commands.</p>
CMI	<p>Bit 0: Factory setting command (active at 1).</p> <p>Bit 1: Save configuration to EEPROM non-volatile memory command (active at 1). This Bit automatically changes to 0 after the request is taken into account. The command is only active if the drive is stopped, and not in "5-Operation enabled" state. Note: If CMI is a periodic network variable, the PLC program must write it to 0 after the first request is taken into account. The life of the EEPROM memory is limited to 100,000 write operations. Note: If the motor or configuration switching function is active, the configuration in the RAM is saved to the EEPROM in the configuration designated by [Config. Active] (CnFS).</p> <p>Bit 2: Reserved (= 0).</p> <p>Bit 3: Reserved (= 0).</p> <p>Bit 4: Reserved (= 0).</p> <p>Bit 5: Reserved (= 0).</p> <p>Bit 6: Reserved (= 0).</p> <p>Bit 7: Reserved (= 0).</p> <p>Bit 8: Reserved (= 0).</p> <p>Bit 9: Definition of the frequency reference (LFr) and output frequency (rFr) unit: = 0: 0.1 Hz = 1: Standardized value 16 signed bits based on the maximum frequency. The value 32767 corresponds to [Max frequency] (tFr). The default value of [Max frequency] (tFr) is 60 Hz, and the resolution is then approximately 0.0018 Hz. This function has no effect on the speed reference (LFRd) or the output speed (rFRd).</p> <p>Bit 10: Reserved (= 0).</p> <p>Bit 11: Reserved (= 0).</p> <p>Bit 12: Reserved (= 0).</p> <p>Bit 13: Reserved (= 0).</p> <p>Bit 14: Reserved (= 0).</p> <p>Bit 15: Parameter consistency check = 0: The check is activated. Each time a parameter is written, the drive checks the relationship between the written parameter and the configuration in the drive. For example, the [High speed] (HSP) parameter must be less than [Max frequency] (tFr). = 1: The check is deactivated. The drive is locked in stop mode. In this drive state, the configuration can be written parameter by parameter and the drive does not modify the values that are written. The switch from 1 to 0 triggers a calculation of the consistency of the configuration. Some parameters can be modified automatically by the drive.</p>
CRP0 CRP1 CRP2 CRP3 CRP4 CRP5 CRP6 CRP7 CRP8 CRP9 CRPA CRPB CRPC CRPD CRPE CRPF	<p>Bit 0 to Bit 7: Active command channels</p> <p>0 = The terminal board is the active channel.</p> <p>1 = The local keypad is the active channel.</p> <p>2 = The remote keypad is the active channel.</p> <p>3 = Modbus is the active channel.</p> <p>4 = Reserved</p> <p>5 = Reserved</p> <p>6 = CANopen is the active channel.</p> <p>7 = The terminals are the active channel in the +/- speed reference.</p> <p>8 = The remote keypad is the active channel (up-down speed)</p> <p>9 = The network card is the active channel.</p> <p>10 = Reserved</p> <p>11 = Reserved</p> <p>12 = Reserved</p> <p>13 = Reserved</p> <p>14 = Reserved</p> <p>15 = SoMove software is the active channel.</p> <p>Bit 8 to Bit 15: Active reference channels</p> <p>0 = The terminals are the active channel via an analog input.</p> <p>1 = The local keypad is the active channel.</p> <p>2 = The remote keypad is the active channel.</p> <p>3 = Modbus is the active channel.</p> <p>4 = Reserved</p>

	<p>5 = Reserved</p> <p>6 = CANopen is the active channel.</p> <p>7 = The terminals are the active channel in the +/- speed reference.</p> <p>8 = The remote keypad is the active channel (up-down speed)</p> <p>9 = The network card is the active channel.</p> <p>10 = Reserved</p> <p>11 = Reserved</p> <p>12 = Reserved</p> <p>13 = Reserved</p> <p>14 = Reserved</p> <p>15 = SoMove software is the active channel.</p>
<p>ETA</p> <p>EP0</p> <p>EP1</p> <p>EP2</p> <p>EP3</p> <p>EP4</p> <p>EP5</p> <p>EP6</p> <p>EP7</p> <p>EP8</p> <p>EP9</p> <p>EPA</p> <p>EPB</p> <p>EPC</p> <p>EPD</p> <p>EPE</p> <p>EPF</p>	<p>Possible values in CiA402 profile, separate or not separate mode:</p> <p>Bit 0: = 1: "Ready to switch on", awaiting power section line supply</p> <p>Bit 1: = 1: "Switched on", ready</p> <p>Bit 2: = 1: "Operation enabled", running</p> <p>Bit 3: = 1: Fault detection</p> <p>Bit 4: "Voltage enabled", power section line supply present</p> <p>= 0: Power section line supply absent</p> <p>= 1: Power section line supply present</p> <p>When the drive is powered by the power section only, this bit is always at 1.</p> <p>Bit 5: = 0: Quick stop/Emergency stop</p> <p>Bit 6: = 1: "Switched on disabled", power section line supply locked</p> <p>Bit 7: Warning, alarm</p> <p>= 0: No alarm</p> <p>= 1: Alarm</p> <p>Bit 8: Reserved (= 0)</p> <p>Bit 9: Remote: command or reference via the network</p> <p>= 0: Command or reference via the graphic display terminal or the remote display terminal</p> <p>= 1: Command or reference via the network</p> <p>Bit 10: Target reference reached</p> <p>= 0: The reference is not reached</p> <p>= 1: The reference has been reached</p> <p>When the drive is in speed mode, this is the speed reference.</p> <p>Bit 11: "Internal limit active", reference outside limits</p> <p>= 0: The reference is within the limits</p> <p>= 1: The reference is not within the limits</p> <p>When the drive is in speed mode, the limits are defined by the [Low speed] (LSP) and [High speed] (HSP) parameters.</p> <p>Bit 12: Reserved (= 0)</p> <p>Bit 13: Reserved (= 0)</p> <p>Bit 14: "Stop key", STOP via stop key</p> <p>= 0: STOP key not pressed</p> <p>= 1: Stop triggered by the STOP key on the graphic display terminal or the remote display terminal</p> <p>Bit 15: "Direction", direction of rotation</p> <p>= 0: Forward rotation at output</p> <p>= 1: Reverse rotation at output</p> <p>The combination of Bits 0, 1, 2, 4, 5 and 6 defines the state in the DSP 402 state chart (see the Communication manuals).</p> <p>Possible values in the I/O profile:</p> <p>Note: The value is identical in the CiA402 profile and the I/O profile. In the I/O profile, the description of the values is simplified and does not refer to the CiA402 (Drivecom) state chart.</p> <p>Bit 0: Reserved (= 0 or 1)</p> <p>Bit 1: Ready</p> <p>= 0: Not ready</p> <p>= 1: Ready</p> <p>Bit 2: Running</p> <p>= 0: The drive will not start if a reference other than zero is applied.</p> <p>= 1: Running, if a reference other than zero is applied, the drive can start.</p> <p>Bit 3: Fault</p> <p>= 0: No fault</p> <p>= 1: Fault</p> <p>Bit 4: Power section line supply present</p> <p>= 0: Power section line supply absent</p> <p>= 1: Power section line supply present</p> <p>Bit 5: Reserved (= 1)</p>

	<p>Bit 6: Reserved (= 0 or 1)</p> <p>Bit 7: Alarm = 0: No alarm = 1: Alarm</p> <p>Bit 8: Reserved (= 0)</p> <p>Bit 9: Command via a network = 0: Command via the terminals or the graphic display terminal = 1: Command via a network</p> <p>Bit 10: Reference reached = 0: The reference is not reached = 1: The reference has been reached</p> <p>Bit 11: Reference outside limits = 0: The reference is within the limits = 1: The reference is not within the limits When the drive is in speed mode, the limits are defined by LSP and HSP parameters.</p> <p>Bit 12: Reserved (= 0)</p> <p>Bit 13: Reserved (= 0)</p> <p>Bit 14: Stop via STOP key = 0: STOP key not pressed = 1: Stop triggered by the STOP key on the graphic display terminal or the remote display terminal</p> <p>Bit 15: Direction of rotation = 0: Forward rotation at output = 1: Reverse rotation at output</p>
ETI IP0 IP1 IP2 IP3 IP4 IP5 IP6 IP7 IP8 IP9 IPA IPB IPC IPD IPE IPF	<p>Bit 0: = 1: Access to the EEPROM non-volatile memory in progress</p> <p>Bit 1: = 0: No parameter consistency check = 1: Parameter consistency check</p> <p>Bit 2: = 0: The drive is not in fault state or a fault is detected = 1: The drive is in fault state but the fault is no longer present (not reset)</p> <p>Bit 3: Reserved (= 0).</p> <p>Bit 4: = 1: The drive is in speed mode</p> <p>Bit 5: = 1: DC injection braking (identical to LSR4, bit 11)</p> <p>Bit 6: = 0: Drive in steady state = 1: Drive in transient state</p> <p>Bit 7: = 1: Motor thermal state threshold reached for the active motor</p> <p>Bit 8: = 1: Overbraking (identical to LSR5, bit 1)</p> <p>Bit 9: = 1: Acceleration in progress (identical to LSR4, bit 13)</p> <p>Bit 10: = 1: Deceleration in progress (identical to LSR4, bit 14)</p> <p>Bit 11: = 1: Current limit in progress</p> <p>Bit 12: = 1: Fast stop in progress (identical to LSR4, bit 15)</p> <p>Bit 13: bit 13 = 0 and bit 14 = 0: Drive controlled by terminal or local keypad</p> <p>Bit 14: bit 13 = 1 and bit 14 = 0: Drive controlled by remote keypad bit 13 = 0 and bit 14 = 1: Drive controlled by Modbus bit 13 = 1 and bit 14 = 1: Drive controlled by CANopen or the network card</p> <p>Bit 15: = 0: Forward operation applied before the ramp = 1: Reverse operation applied before the ramp</p>
EWE	<p>Bit 0: = 1: Enable Web</p> <p>Bit 1: = 1: Enable Email</p> <p>Bit 2: Reserved (= 0).</p> <p>Bit 3: Reserved (= 0).</p> <p>Bit 4: Reserved (= 0).</p> <p>Bit 5: Reserved (= 0).</p> <p>Bit 6: Reserved (= 0).</p> <p>Bit 7: Reserved (= 0).</p> <p>Bit 8: Reserved (= 0).</p> <p>Bit 9: Reserved (= 0).</p> <p>Bit 10: Reserved (= 0).</p> <p>Bit 11: Reserved (= 0).</p> <p>Bit 12: Reserved (= 0).</p> <p>Bit 13: Reserved (= 0).</p> <p>Bit 14: Reserved (= 0).</p> <p>Bit 15: Reserved (= 0).</p>
FrY	<p>Selection of menus to be loaded.</p> <p>Bit 0: = 1: [All] (ALL): all parameters.</p>

	<p>Bit 1: = 1:[Drive menu] (drM): The [1 DRIVE MENU] (drl-) menu without [COMMUNICATION] (COM-). In the [2.4 DISPLAY CONFIG.] menu, [Return std name] returns to [No].</p> <p>Bit 2: Reserved (=0 ou 1).</p> <p>Bit 3: = 1:[Motor param] (MOt): Motor parameters,</p> <p>The following selection is accessible only if [Config. Source] (FCSI) = [Macro-Conf] (InI) :</p> <p>Bit 4: = 1:[Comm. menu] (COM): The [COMMUNICATION] (COM-) menu without either [Scan. In1 address] (nMA1) to [Scan. In8 address] (nMA8) or [Scan.Out1 address] (nCA1) to [Scan.Out8 address] (nCA8).</p> <p>Bit 5: Reserved (=0 ou 1).</p> <p>Bit 6: Reserved (=0 ou 1).</p> <p>Bit 7: = 1:[Display config.] (dIS): The [2.3 MONITORING CONFIG.] (MCF-) menu</p> <p>Bit 8: Reserved (=0 ou 1).</p> <p>Bit 9: Reserved (=0 ou 1).</p> <p>Bit 10: Reserved (=0 ou 1).</p> <p>Bit 11: Reserved (=0 ou 1).</p> <p>Bit 12: Reserved (=0 ou 1).</p> <p>Bit 13: Reserved (=0 ou 1).</p> <p>Bit 14: Reserved (=0 ou 1).</p> <p>Bit 15: Reserved (=0 ou 1).</p> <p>See the multiple selection procedure for the integrated display terminal and for the graphic display terminal. Note: In factory configuration and after a return to "factory settings", [PARAMETER GROUP LIST] will be empty.</p>
<p>IL11 IL1R</p>	<p>Bit 0: Value of LI1.</p> <p>Bit 1: Value of LI2.</p> <p>Bit 2: Value of LI3.</p> <p>Bit 3: Value of LI4.</p> <p>Bit 4: Value of LI5</p> <p>Bit 5: Value of LI6</p> <p>Bit 6: Reserved (= 0).</p> <p>Bit 7: Reserved (= 0).</p> <p>Bit 8: Reserved (= 0).</p> <p>Bit 9: Reserved (= 0).</p> <p>Bit 10: Reserved (= 0).</p> <p>Bit 11: Value of LI11</p> <p>Bit 12: Value of LI12</p> <p>Bit 13: Value of LI13</p> <p>Bit 14: Value of LI14</p> <p>Bit 15: Value of LI15</p>
<p>ST00</p>	<p>Bit 0: (JAMP) : An anti-jam request is pending</p> <p>Bit 1: (JAMR) : An anti-jam sequence is running</p> <p>Bit 2: (FILL) : Pipe fill sequence is running</p> <p>Bit 3: (IPPC) : Inlet pressure compensation is running</p> <p>Bit 4: (SLM) : Stop asked by a "sleeping" function</p> <p>Bit 5: (LDA) : Low demand active (Wave 2)</p> <p>Bit 6: (PPON) : Priming pump is running</p> <p>Bit 7: (JPON) : Jockey pump is running</p> <p>Bit 8: (SLPP) : Sleep is pending</p> <p>Bit 9: (SLPB) : Sleep Boost phase is running</p> <p>Bit 10: (SLP) : Application Sleeping</p> <p>Bit 11: (ASLC) : Advanced Sleep Checking is active</p> <p>Bit 12: Reserved (= 0).</p> <p>Bit 13: Reserved (= 0).</p> <p>Bit 14: Reserved (= 0).</p> <p>Bit 15: Reserved (= 0).</p>
<p>ST01</p>	<p>Bit 0: Reserved (=0).</p> <p>Bit 1: Reserved (=0).</p> <p>Bit 2: Reserved (=0).</p> <p>Bit 3: Reserved (=0).</p> <p>Bit 4: Reserved (=0).</p> <p>Bit 5: Reserved (=0).</p> <p>Bit 6: Reserved (=0).</p> <p>Bit 7: Reserved (=0).</p>

	<p>Bit 8: Reserved (=0). Bit 9: Reserved (=0). Bit 10: Reserved (=0). Bit 11: Reserved (=0).</p> <p>Bit 12: Reserved (=0). Bit 13: Reserved (=0). Bit 14: Reserved (=0). Bit 15: Reserved (=0).</p>
ST02	<p>Bit 0: (CNF0) : Configuration 1 is used Bit 1: Reserved (=0). Bit 2: Reserved (=0). Bit 3: Reserved (=0).</p> <p>Bit 4: (CFP1) : Parameter set 1 is used Bit 5: (CFP2) : Parameter set 2 is used Bit 6: (CFP3) : Parameter set 3 is used Bit 7: (CFP4) : Parameter set 4 is used</p> <p>Bit 8: Reserved (=0). Bit 9: Reserved (=0). Bit 10: Reserved (=0). Bit 11: Reserved (=0).</p> <p>Bit 12: Reserved (=0). Bit 13: Reserved (=0). Bit 14: Reserved (=0). Bit 15: Reserved (=0).</p>
ST03	<p>Bit 0: (FLO) : Drive in forced local mode Bit 1: (FR2) : Reference channel is channel 2 Bit 2: (FR1B) : Reference channel is channel 1, and FR1B is used Bit 3: (FR1) : Reference channel is channel 1 (FR1 or FR1B is used)</p> <p>Bit 4: (CD1) : Command channel is channel 1 Bit 5: (CD2) : Command channel is channel 2 Bit 6: (RFC) : Reference channel : 0-> channel1, 1-> channel 2 Bit 7: (RCB) : 0: FR1, FR1B ?</p> <p>Bit 8: (CCS) : Command channel : 0-> channel 1, 1-> channel 2</p> <p>Bit 9: (BMP) : Bump Less Channel Bit 10: Reserved (=0). Bit 11: Reserved (=0).</p> <p>Bit 12: Reserved (=0). Bit 13: Reserved (=0). Bit 14: Reserved (=0). Bit 15: Reserved (=0).</p>
ST04	<p>Bit 0: (FLT) : Drive is in fault state Bit 1: (AUTO) : Automatic restart attempts in progress Bit 2: (RDY) : Drive is in ready state Bit 3: (RUN) : A gating order is set (there is potentially current in the motor)</p> <p>Bit 4: (DBL) : Powerstage is supply (DC bus charged) Bit 5: (CTL) : Controlled stop on power loss in progress Bit 6: (STO) : STO function activated Bit 7: (FST) : A fast stop request is on going</p> <p>Bit 8: (FRF) : Reaction on event / fallback speed Bit 9: (RLS) : Reaction on event / maintain speed Bit 10: (STT) : Reaction on event / Stop on STT without tripping in fault Bit 11: (IDLE) : Stop and Go idle state (FF343)</p> <p>Bit 12: Reserved (=0). Bit 13: Reserved (=0). Bit 14: Reserved (=0). Bit 15: Reserved (=0).</p>
ST05	<p>Bit 0: (LLC) : The drive asks to close the line contactor</p>

	<p>Bit 1: (OCC) : The drive asks to close the output contactor (Controlled downstream contactor)</p> <p>Bit 2: (SOC) : The drive has detected that the output contactor is open (Uncontrolled downstream contactor)</p> <p>Bit 3: Reserved (=0).</p> <p>Bit 4: Reserved (=0).</p> <p>Bit 5: Reserved (=0).</p> <p>Bit 6: Reserved (=0).</p> <p>Bit 7: Reserved (=0).</p> <p>Bit 8: Reserved (=0).</p> <p>Bit 9: Reserved (=0).</p> <p>Bit 10: Reserved (=0).</p> <p>Bit 11: Reserved (=0).</p> <p>Bit 12: Reserved (=0).</p> <p>Bit 13: Reserved (=0).</p> <p>Bit 14: Reserved (=0).</p> <p>Bit 15: Reserved (=0).</p>
ST06	<p>Bit 0: (ACC) : Drive in acceleration</p> <p>Bit 1: (DEC) : Drive in deceleration</p> <p>Bit 2: (SRA) : Frequency reference reached</p> <p>Bit 3: (MFRD) : Motor running in Forward</p> <p>Bit 4: (MRRS) : Motor running in Reverse</p> <p>Bit 5: (ATS) : Torque on the motor is negativ</p> <p>Bit 6: (IDC) : DC injection is running (automatic or by order)</p> <p>Bit 7: (FLU) : Motor fluxing in progress</p> <p>Bit 8: (FLX) : Motor fluxed</p> <p>Bit 9: (TUN) : Autotune in progress</p> <p>Bit 10: (MCP) : Motor current present</p> <p>Bit 11: (RP2) : Ramp switching state : 0-> ramp 1, 1-> ramp 2</p> <p>Bit 12: Reserved (= 0)</p> <p>Bit 13: Reserved (= 0)</p> <p>Bit 14: Reserved (= 0)</p> <p>Bit 15: Reserved (= 0)</p>
ST07	<p>Bit 0: (AG1) : One of the alarm of alarm group 1 is active</p> <p>Bit 1: (AG2) : One of the alarm of alarm group 2 is active</p> <p>Bit 2: (AG3) : One of the alarm of alarm group 3 is active</p> <p>Bit 3: (AG4) : One of the alarm of alarm group 4 is active</p> <p>Bit 4: (AG5) : One of the alarm of alarm group 5 is active</p> <p>Bit 5: Reserved (= 0)</p> <p>Bit 6: Reserved (= 0)</p> <p>Bit 7: Reserved (= 0)</p> <p>Bit 8: (LCA1) : Life Cycle Alarm 1 alarm</p> <p>Bit 9: (LCA2) : Life Cycle Alarm 2 alarm</p> <p>Bit 10: Reserved (= 0)</p> <p>Bit 11: Reserved (= 0)</p> <p>Bit 12: Reserved (= 0)</p> <p>Bit 13: Reserved (= 0)</p> <p>Bit 14: Reserved (= 0)</p> <p>Bit 15: Reserved (= 0)</p>
ST08	<p>Bit 0: (DRYA) : Dry Running Alarm</p> <p>Bit 1: (PLFA) : Pump Low Flow Alarm</p> <p>Bit 2: (HFPA) : High Flow Alarm</p> <p>Bit 3: (IPPA) : Inlet Pressure Protection Alarm</p> <p>Bit 4: (OPLA) : Outlet Pressure Low Alarm</p> <p>Bit 5: (OPHA) : Outlet Pressure High Alarm</p> <p>Bit 6: (PCPA) : Cyclic Start Protection Alarm</p> <p>Bit 7: (JAMA) : Antijam alarm is raised</p> <p>Bit 8: (LFA) : Low Flow Alarm</p> <p>Bit 9: (LPA) : Low pressure alarm is raised</p> <p>Bit 10: (FSA) : Flow limit function activated (FL_Mode_On)</p> <p>Bit 11: (OPSA) : Outlet Pressure High Switch Alarm</p>

	<p>Bit 12: Reserved (= 0) Bit 13: Reserved (= 0) Bit 14: Reserved (= 0) Bit 15: Reserved (= 0)</p>
ST09	<p>Bit 0: (PFA) : alarm on PID Feedback Bit 1: (PFAH) : PID feedback high threshold reached Bit 2: (PFAL) : PID feedback low threshold reached Bit 3: (PISH) : PI feedback monitoring alarm is raised</p> <p>Bit 4: Reserved (= 0) Bit 5: Reserved (= 0) Bit 6: Reserved (= 0) Bit 7: Reserved (= 0)</p> <p>Bit 8: Reserved (= 0) Bit 9: Reserved (= 0) Bit 10: Reserved (= 0) Bit 11: (PEE) : alarm on PID error</p> <p>Bit 12: Reserved (= 0) Bit 13: Reserved (= 0) Bit 14: Reserved (= 0) Bit 15: Reserved (= 0)</p>
ST10	<p>Bit 0: Reserved (=0). Bit 1: Reserved (=0). Bit 2: Reserved (=0). Bit 3: Reserved (=0).</p> <p>Bit 4: Reserved (=0). Bit 5: Reserved (=0). Bit 6: Reserved (=0). Bit 7: Reserved (=0).</p> <p>Bit 8: Reserved (=0). Bit 9: Reserved (=0). Bit 10: Reserved (=0). Bit 11: Reserved (=0).</p> <p>Bit 12: Reserved (=0). Bit 13: Reserved (=0). Bit 14: Reserved (=0). Bit 15: Reserved (=0).</p>
ST11	<p>Bit 0: (TP2A) : Temperature Protection AI2 Alarm Bit 1: (TP3A) : Temperature Protection AI3 Alarm Bit 2: (TP4A) : Temperature Protection AI4 Alarm Bit 3: (TP5A) : Temperature Protection AI5 Alarm</p> <p>Bit 4: Reserved (=0). Bit 5: Reserved (=0). Bit 6: Reserved (=0). Bit 7: Reserved (=0).</p> <p>Bit 8: Reserved (=0). Bit 9: Reserved (=0). Bit 10: Reserved (=0). Bit 11: Reserved (=0).</p> <p>Bit 12: Reserved (=0). Bit 13: Reserved (=0). Bit 14: Reserved (=0). Bit 15: Reserved (=0).</p>
ST12	<p>Bit 0: (AP1) : 4-20 loss alarm on AI1 Bit 1: (AP2) : 4-20 loss alarm on AI2 Bit 2: (AP3) : 4-20 loss alarm on AI3 Bit 3: (AP4) : 4-20 loss alarm on AI4</p> <p>Bit 4: (AP5) : 4-20 loss alarm on AI5 Bit 5: Reserved (=0). Bit 6: Reserved (=0).</p>

	<p>Bit 7: Reserved (=0).</p> <p>Bit 8: Reserved (=0).</p> <p>Bit 9: Reserved (=0).</p> <p>Bit 10: Reserved (=0).</p> <p>Bit 11: Reserved (=0).</p> <p>Bit 12: Reserved (=0).</p> <p>Bit 13: Reserved (=0).</p> <p>Bit 14: Reserved (=0).</p> <p>Bit 15: Reserved (=0).</p>
ST13	<p>Bit 0: (THA) : drive overheating alarm is raised</p> <p>Bit 1: (TJA) : alarm on IGBT thermal state</p> <p>Bit 2: (FCTA) : Fan Counter Speed alarm</p> <p>Bit 3: (FFDA) : Fan feedback alarm is raised</p> <p>Bit 4: Reserved (=0).</p> <p>Bit 5: (EFA) : external alarm is raised</p> <p>Bit 6: (USA) : undervoltage alarm is raised</p> <p>Bit 7: (UPA) : controlled stop on power loss threshold id reached</p> <p>Bit 8: (OBR) : Impossible to follow the customer ramp during deceleration</p> <p>Bit 9: Reserved (=0).</p> <p>Bit 10: Reserved (=0).</p> <p>Bit 11: Reserved (=0).</p> <p>Bit 12: Reserved (=0).</p> <p>Bit 13: Reserved (=0).</p> <p>Bit 14: Reserved (=0).</p> <p>Bit 15: Reserved (=0).</p>
ST14	<p>Bit 0: (FTA) : Motor frequency high threshold 1 reached</p> <p>Bit 1: (FTAL) : Motor frequency low threshold 1 reached</p> <p>Bit 2: (FQLA) : Motor frequency high threshold 2 reached</p> <p>Bit 3: (F2AL) : Motor frequency low threshold 2 reached</p> <p>Bit 4: (FLA) : HighSpeedReached function result</p> <p>Bit 5: (RTAH) : Reference frequency high threshold reached</p> <p>Bit 6: (RTAL) : Reference frequency low threshold reached</p> <p>Bit 7: (F2A) : Frequency level reached (frequency meter)</p> <p>Bit 8: Reserved (=0).</p> <p>Bit 9: Reserved (=0).</p> <p>Bit 10: Reserved (=0).</p> <p>Bit 11: Reserved (=0).</p> <p>Bit 12: Reserved (=0).</p> <p>Bit 13: Reserved (=0).</p> <p>Bit 14: Reserved (=0).</p> <p>Bit 15: Reserved (=0).</p>
ST15	<p>Bit 0: (CTA) : Motor current high threshold reached</p> <p>Bit 1: (CTAL) : Motor current low threshold reached</p> <p>Bit 2: (TTHA) : Motor torque high threshold reached</p> <p>Bit 3: (TTLA) : Motor torque low threshold reached</p> <p>Bit 4: (ULA) : Underload is detected</p> <p>Bit 5: (OLA) : Overload is detected</p> <p>Bit 6: (CLI) : current or torque limitation is running</p> <p>Bit 7: Reserved (=0).</p> <p>Bit 8: Reserved (=0).</p> <p>Bit 9: (POWD) : Electrical Power Drift alarm</p> <p>Bit 10: (PTHA) : Power high threshold reached</p> <p>Bit 11: (PTHL) : Power Low threshold reached</p> <p>Bit 12: Reserved (=0).</p> <p>Bit 13: Reserved (=0).</p> <p>Bit 14: Reserved (=0).</p> <p>Bit 15: Reserved (=0).</p>
ST16	<p>Bit 0: (TAD) : DriveThermalThresholdReached function result</p> <p>Bit 1: (TSA) : MotorThermalThresholdReached function result (motor 1)</p>

	<p>Bit 2: Reserved (=0). Bit 3: Reserved (=0).</p> <p>Bit 4: Reserved (=0). Bit 5: Reserved (=0). Bit 6: Reserved (=0). Bit 7: Reserved (=0).</p> <p>Bit 8: Reserved (=0). Bit 9: Reserved (=0). Bit 10: Reserved (=0). Bit 11: Reserved (=0).</p> <p>Bit 12: Reserved (=0). Bit 13: Reserved (=0). Bit 14: Reserved (=0). Bit 15: Reserved (=0).</p>
ST17	<p>Bit 0: (CAS1) : Customer Alarm 1 active Bit 1: (CAS2) : Customer Alarm 2 active Bit 2: (CAS3) : Customer Alarm 3 active Bit 3: (CAS4) : Customer Alarm 4 active</p> <p>Bit 4: (CAS5) : Customer Alarm 5 active Bit 5: Reserved (=0). Bit 6: Reserved (=0). Bit 7: Reserved (=0).</p> <p>Bit 8: Reserved (=0). Bit 9: Reserved (=0). Bit 10: Reserved (=0). Bit 11: Reserved (=0).</p> <p>Bit 12: Reserved (=0). Bit 13: Reserved (=0). Bit 14: Reserved (=0). Bit 15: Reserved (=0).</p>
OL1R	<p>Bit 0: Value of R1. Bit 1: Value of R2. Bit 2: Value of R3. Bit 3: Value of option R4.</p> <p>Bit 4: Value of option R5. Bit 5: Value of option R6. Bit 6: Reserved (= 0). Bit 7: Reserved (= 0).</p> <p>Bit 8: Reserved (= 0). Bit 9: Reserved (= 0). Bit 10: Reserved (= 0). Bit 11: Reserved (= 0).</p> <p>Bit 12: Value of DO1. Bit 13: Value of DO2. Bit 14: Reserved (= 0). Bit 15: Reserved (= 0).</p> <p>The outputs (relays or logic outputs) can be controlled by the network. The outputs to control should not be assigned to a function of the drive, otherwise the writing is without effect.</p>